

Romil Shah

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EDUCATION

Northeastern University, Boston, MA

Master of Science in Electrical and Computer Engineering

Dec 2017

Concentration: Computer Vision, Machine Learning and Algorithms (CVLA)

Nirma University, Ahmedabad, India

Bachelor of Technology in Electronics and Communication Engineering

May 2014

PROFESSIONAL EXPERIENCE

Amazon Web Services, San Francisco CA

Sr. Applied Scientist

May 2023 - Present

- Lead and manage development of GenAI training and inference pipelines for LLMs, VLMs
- EdgeFM Accelerator to scale FM inference for cheaper, faster and more efficient FM deployment

Applied Scientist II

Aug 2021 – May 2023

- Create/Deploy/Manage Deep Learning pipelines for Cloud and IoT Edge; Design AWS architecture for Edge IoT based ML solutions
- Lead multiple engagements to solve CVML related customer requirements; Dive deep to improve AI/ML AWS Services
- Own and Manage customized Edge ML pipelines; Develop MLOps for customers

Dolby Laboratories, Sunnyvale CA

Sr. Computer Vision & Imaging Engineer

Dec 2019 – Aug 2021

- Lead and Design/Optimize/Implement/Deploy CV + DL application pipelines for Dolby ATG and Dolby iAPI
- Train/Deploy/Optimize DL models for various Dolby vision applications
- Multimodal pipeline for 2D segmentation, classification, detection, GANs and pose estimation
- Optimizing model deployment for embedded devices for real-time applications

Strada Labs, San Francisco CA

Co-Founder and CTO (Part-Time)

Dec 2018 – Dec 2019
(Part-Time)

- Co-Founded the startup which focused on using Computer Vision for analyzing urban movements
- Analyze patterns to aid urban planning for creating smarter and safer cities

Ford Research and Innovation Center, Ford Motor Company, Palo Alto CA

AI Research Engineer

Jan 2018 – Dec 2019

- Application of research on AI & Mobility projects for AVs and Connected vehicles
- Working on projects for Ford Performance Racing (NASCAR)
- Research in CV/ML/DL/RL to publish internally & externally; Filing mobility & AI related invention; 7 Patents pending
- Worked on 3D data using SfM, LiDAR data
- Using Deep Learning for Motion Compensation-Estimation, Video Compression, Frame Interpolation; Pose estimation

Volvo Construction Equipment, Shippensburg PA

Computer Vision Research Engineer Co-Op (8-month-internship)

Jan 2017 – Aug 2017

- Object recognition-detection-tracking on CUDA-based embedded systems for semi autonomous construction vehicles
- Using DNN architecture and DL frameworks Caffe and Caffe2; Camera Calibration; Increased FPS by mixed precision training/deployment
- Worked on RADAR and monocular/stereo camera; handcrafted features for detection-tracking; TCP/UDP based communication and sensor fusion using ZeroMQ

ReGameVR Lab, Boston MA

Research Assistant

July 2016 – Dec 2016

- Rehabilitation oriented frontal/profile face detection using OpenCV libraries and Haar-like features using sensor fusion of camera system and IMUs; Using Kinect for tracking human body-joints to improve rehabilitation techniques and create a labelled dataset; UDP for IoT connection between Raspberry Pi and Arduino

Tellmate Helper Pvt. Ltd., Ahmedabad INDIA

Chief Developer and Co-Founder

May 2014 -Aug 2015

- Contributed in making of 'Tellmate', a device made using Kinect 360 and Intel RealSense camera integrated with PandaBoard ES for visually impaired people; Real time OCR, Facial Recognition;
- Selected for Top 20 startups in India from 1.9k participants; 200k INR seed funding by Intel Digital India challenge 2015

Florida Atlantic University, Multimedia Lab, Boca Raton FL

Summer Research Intern

May 2013 – July 2013

- Video processing, scene analysis-characterization-clustering, compression using motion estimation and motion vectors; using X264 and FFMPEG

PATENTS AND PUBLICATIONS

- Shah, R., et al. 2024. Systems and methods for tracking luggage in a vehicle. U.S. Patent Number 11,882,500. Granted Jan 2024.
- Shah, R., et al. 2023. Optimized recharging of electrical vehicles. U.S. Patent Number 11,609,571. Granted Mar 2023.
- Shah, R., et al. 2023. Vehicle damage identification and incident management systems and methods. U.S. Patent Number 11,562,570. Granted Jan 2023.
- Shah, R., et al. 2022. Vehicle yield decision. U.S. Patent Number 11,338,810. Granted May 2022.
- Shah, R., et al. 2019. Systems and Methods for seat selection in a vehicle of a ride service. U.S. Patent Number 11,170,459. Granted Nov 2021.
- Shah, R., et al. 2019. Systems and Methods of preventing removal of items from vehicles by improper parties. U.S. Patent Number 11,295,148. Granted April 2022.
- Shah, R., et al. 2019. Vehicle Yield Decision. U.S. Patent Number 11,338,810. Filed Feb 2020. Granted May 2022.
- Shah, R., et al. 2019. Vehicle Damage Identification and Incident Management Systems and Methods. U.S. Patent Application 20220108115, filed October 2020. Patent Pending.
- Shah, R., et al. 2019. Offline Proximity Rideshare Booking System. U.S. Patent Application 20210090067. Filed Sept 2019. Patent Pending.
- Shah, R., et al. 2019. Systems and Methods for tracking Luggage in a Vehicle. U.S. Patent Application 20220141621. Filed November 2020. Patent Pending.
- Rivera, A., et al. 2018. Object Locator with Fiducial Marker. U.S. Patent Number 11,010,919, Granted May 2018.
- Balasubramanian, SN., et al. 2019. Ride Request Evaluation Systems and Methods. U.S. Patent Application 20200293953. Filed May 2019. Patent Pending.
- McKenzie, M., et al. 2019. Optimized Recharging of Autonomous Vehicles. U.S. Patent Application 202102255633. Filed Feb 2020. Patent Pending.
- Patel, S., Shah, R. 2013. Femtophotography for detection of microbends in step index fiber. IEEE INDICON'13, IIT Bombay, India

PROJECTS

Graduate Projects:

- Detection-Tracking-Following using Toyota HSR; sensor fusion with ROS
- Benchmarking of algorithms for SPARC and x86 systems; Neural Network based Branch Predictor
- Computer Vision: Motion detection, Eigen-faces using PCA, Feature extraction techniques like SIFT & SURF, Image stitching, Barrel distortion, Surround (Bird-Eye) View
- Document Scanner: Automated edge and corner-based document detection with perspective warping

Hackathons:

- *MintMo, PennApps (Spring 2016)*: Using REST API, Capital-One API and Twilio API, built a real time NLP based money transfer application using SMS
- *MyoWalk, BostonHacks (Fall 2015)*: *Gait pattern analysis using Myo Armband on legs; Fall detection; Parkinson's gait detection*
- *AI21Labs, (Dec 2023)*: *Grounded content generation for Amazon advertisements using GenAI*

SKILLS

- **Operating Systems:** Linux, Windows, Mac
- **Simulators:** MATLAB, Simulink, WireShark
- **Familiar with:** CUDA, LiDAR, PCL, ROS, SLAM
- **Libraries:** OpenCV, ZeroMQ, Gstreamer, Dlib, NumPy, FFmpeg, TFJS, Node.js
- **Programming Languages:** Python, C++, Javascript
- **Deep Learning Tools:** OpenVino, Caffe, PyTorch. TensorFlow, AWS Services